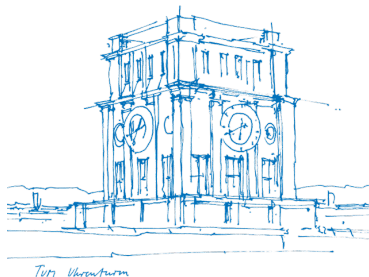


ExaHyPE – An Exascale Hyperbolic PDE Engine

FET-PROACTIVE – Towards Exascale High Performance Computing

Vasco Varduhn

Prague, May 9–10, 2016



Acknowledgements



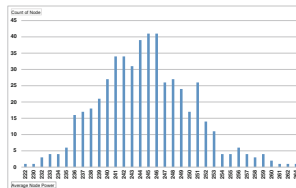
This project has received funding from the European Union's Horizon 2020 research and innovation programme under grant agreement No 671698.

Towards an **Exascale** Hyperbolic PDE Engine

Key Assumptions on Exascale Hardware:

Equal work load will no longer lead to balanced computation time.

Moving data is the thriving constraint for performance and energy consumption.



Results by Wilde et al., ISC'15

Requirements for Exascale Algorithms:

- dynamic load balancing with lightweight adaptive response
- avoid communication and maximise arithmetic intensity
- **plus:** maximise “science per flop”

⇒ **Focus on High Order Discretisation in Space and Time:**

- ADER-DG with local time-stepping and novel FV-based limiting

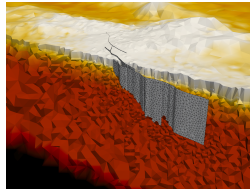
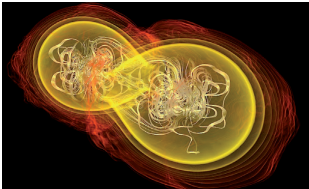
Towards an Exascale Hyperbolic PDE Engine

Key Assumption on Exascale Software:

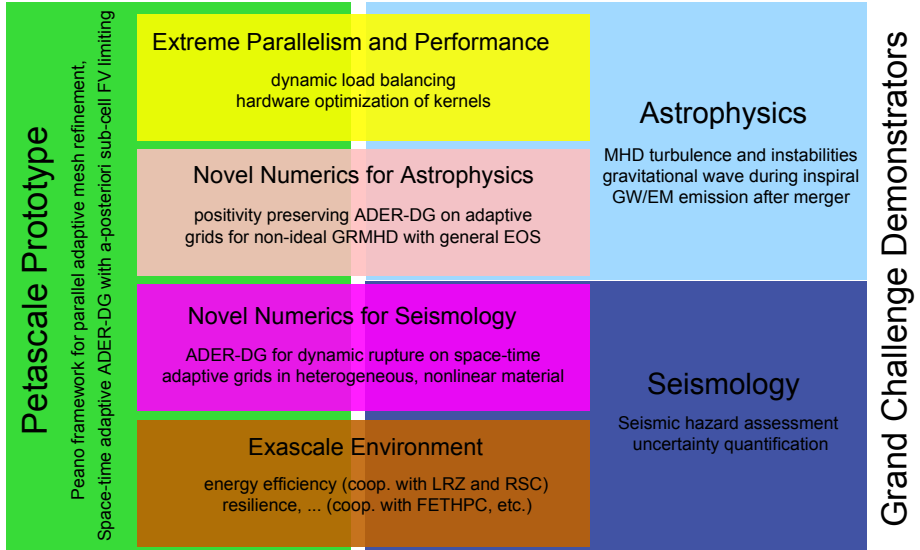
Grand challenge applications require tailoring of existing codes to the specific challenge and cannot rely on general-purpose solutions.

ExaHyPE Goal:

- enable medium-sized interdisciplinary research teams to realise extreme-scale simulations of grand challenges within one year
- focus on hyperbolic conservation laws
- concentrate on two specific grand challenges in the project:



ExaHyPE Work Programme



Towards an Exascale Hyperbolic PDE Engine

User API and Simulation Engine:

- user-defined hyperbolic PDEs
- definition of fluxes and eigenvalues
- toolkit-based code generation

```

computational-domain
  dimension      = 2
  width          = 1.0
  offset         = 0.0, 0.0
  end-time       = 0.4
end computational-domain

solver ADER-DG EulerFlowSolver
  unknowns      = 5
  parameters    = 0
  order         = 7
  kernel        = generic::fluxes::nonlinear
  language      = C
  ...
end solver

shared-memory
  ...
end shared-memory

optimisation
  fuse-algorithmic-steps = on
end optimisation
  
```

```

void flux(Q, f, g) {
  // @todo Please implement
  irho = 1.0/Q[0];
  ...
  f[0] = Q[1];
  f[1] = irho * Q[1] + Q[1] * p;
  f[2] = irho * Q[1] + Q[2];
  f[3] = irho * Q[1] + Q[3];
  f[4] = irho * Q[1] + (Q[4] + p);

  g[0] = Q[2];
  g[1] = irho * Q[2] + Q[1];
  g[2] = irho * Q[2] + Q[2] * p;
  g[3] = irho * Q[2] + Q[3];
  g[4] = irho * Q[2] + (Q[4] + p);
}

void eigenvalues(Q, normal, lambda) {
  // @todo Please implement
}

void adjustSolutionValues(x, w, t, dt, Q) {
  // @todo Please implement
  if(t == 0.0) {
    Q[0] = 1.0;
    Q[1] = Q[2] = Q[3] = 0.0;
    Q[4] = exp(x[0]*x[0])*x[1]*x[1];
  }
}
  
```

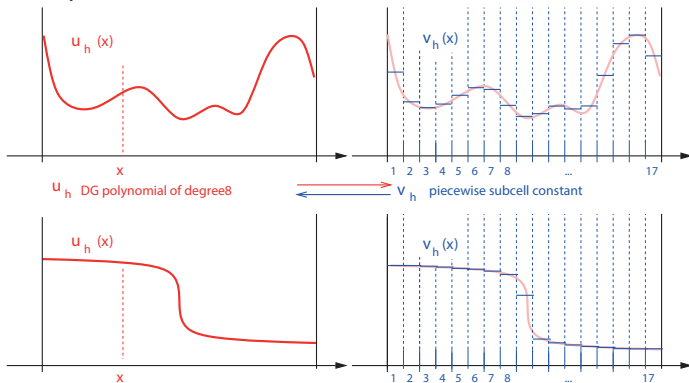
compute kernels

Makefile

Towards an Exascale Hyperbolic PDE Engine

DG with FV-based Subcell Limiting:

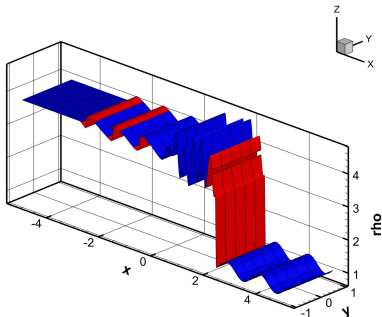
- high-order DG method, high accuracy and compute-bound regimes
- a-posteriori identification of troubled cells
- FV recomputation and DG reconstruction



Towards an Exascale Hyperbolic PDE Engine

DG with FV-based Subcell Limiting:

- high-order DG method, high accuracy and compute-bound regimes
- a-posteriori identification of troubled cells
- FV recomputation and DG reconstruction



ExaHyPE Participants and Pls

University Participants:

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Industry Participants:

- RSC Group (Russia): Alexander Moskovsky

Project Management and Dissemination:

- BayFOR – Bavarian Research Alliance: Robert Iberl

