

ExaHyPE – An Exascale Hyperbolic PDE Engine

FET-PROACTIVE – Towards Exascale High Performance Computing

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TUM Uhrenturm

Acknowledgements



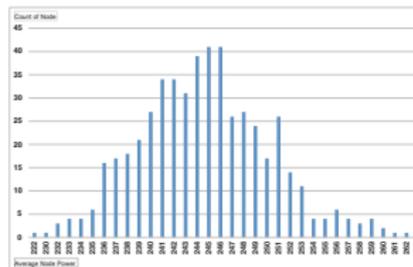
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Towards an Exascale Hyperbolic PDE Engine

Key Assumptions on Exascale Hardware:

Equal work load will no longer lead to balanced computation time.

Moving data is the thriving constraint for performance and energy consumption.



Results by Wilde et al., ISC'15

Requirements for Exascale Algorithms:

- dynamic load balancing with lightweight adaptive response
- avoid communication and maximise arithmetic intensity
- **plus:** maximise “science per flop”

⇒ Focus on High Order Discretisation in Space and Time:

- ADER-DG with local time-stepping and novel FV-based limiting

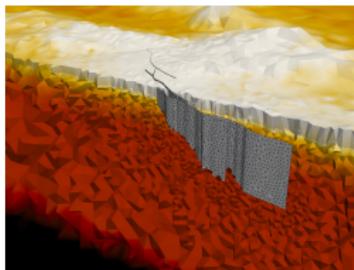
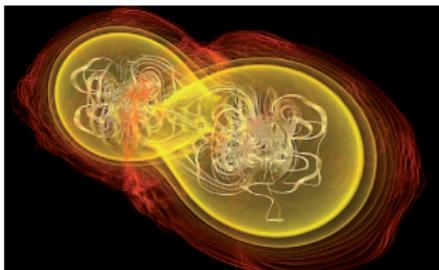
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Key Assumption on Exascale Software:

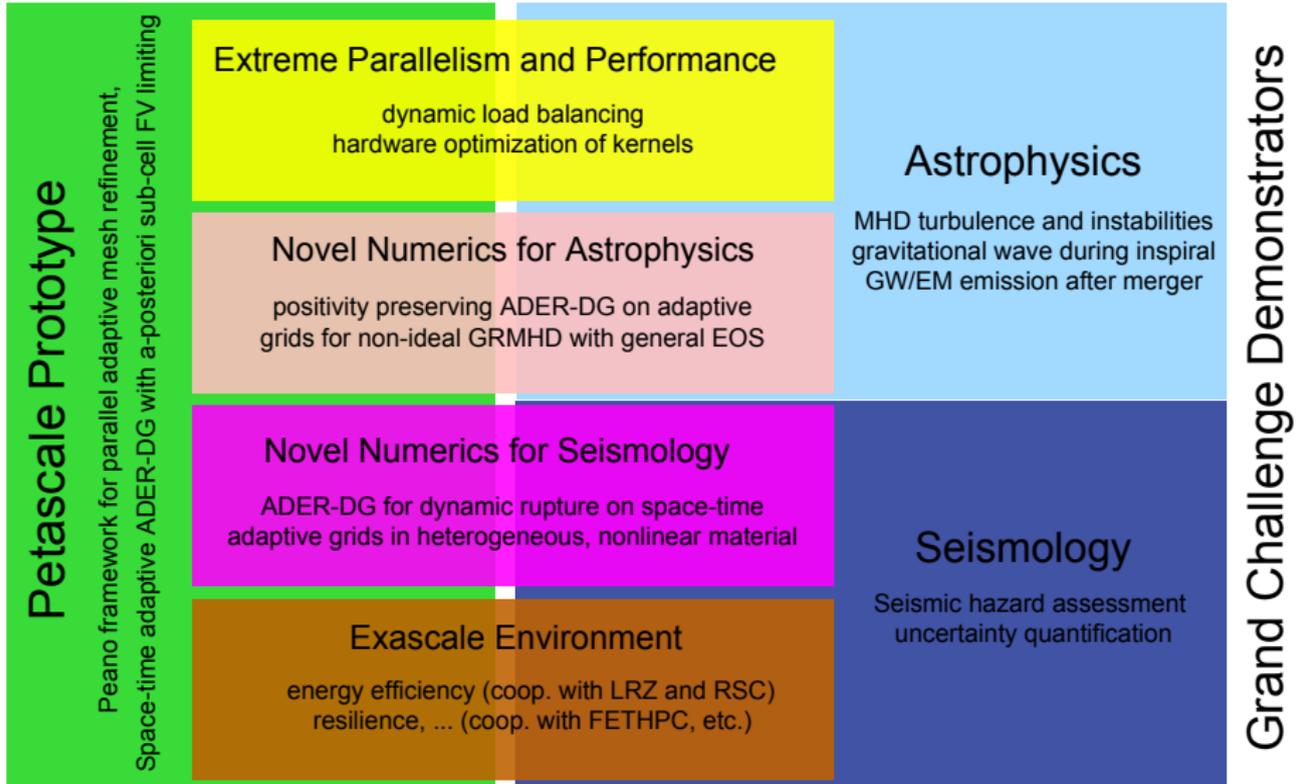
Grand challenge applications require tailoring of existing codes to the specific challenge and cannot rely on general-purpose solutions.

ExaHyPE Goal:

- enable medium-sized interdisciplinary research teams to realise extreme-scale simulations of grand challenges within one year
- focus on hyperbolic conservation laws
- concentrate on two specific grand challenges in the project:



ExaHyPE Work Programme



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User API and Simulation Engine:

- user-defined hyperbolic PDEs
- definition of fluxes and eigenvalues
- toolkit-based code generation

```

computational-domain
  dimension      = 2
  width         = 1.0
  offset        = 0.0, 0.0
  end-time      = 0.4
end computational-domain

solver ADER-DG EulerFlowSolver
  unknowns = 5
  parameters = 0
  order = 7
  kernel = generic::fluxes::nonlinear
  language = C
  ...
end solver

shared-memory
  ...
end shared-memory

optimisation
  fuse-algorithmic-steps = on
end optimisation
  
```

```

void flux(Q, f, g) {
  // TODO Please implement
  irho = 1.0/Q[0];
  ...
  f[0] = Q[1];
  f[1] = irho * Q[1] + Q[1] * p;
  f[2] = irho * Q[1] + Q[2];
  f[3] = irho * Q[1] + Q[3];
  f[4] = irho * Q[1] + (Q[4] + p);

  g[0] = Q[2];
  g[1] = irho * Q[2] + Q[1];
  g[2] = irho * Q[2] + Q[2] * p;
  g[3] = irho * Q[2] + Q[3];
  g[4] = irho * Q[2] + (Q[4] + p);
}

void eigenvalues(Q, normal, lambda) {
  // TODO Please implement
}

void adjustSolutionValues(x, w, t, dt, Q) {
  // TODO Please implement
  if(t == 0.0) {
    Q[0] = 1.0;
    Q[1] = Q[2] = Q[3] = 0.0;
    Q[4] = exp(x[0]*x[0])*(x[1]+x[1]);
  }
}
  
```

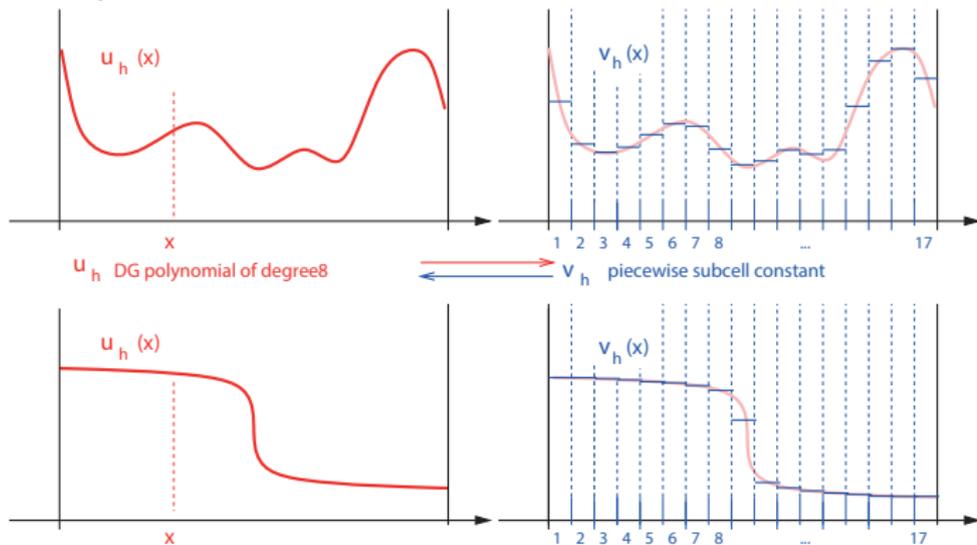
compute kernels

Makefile

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DG with FV-based Subcell Limiting:

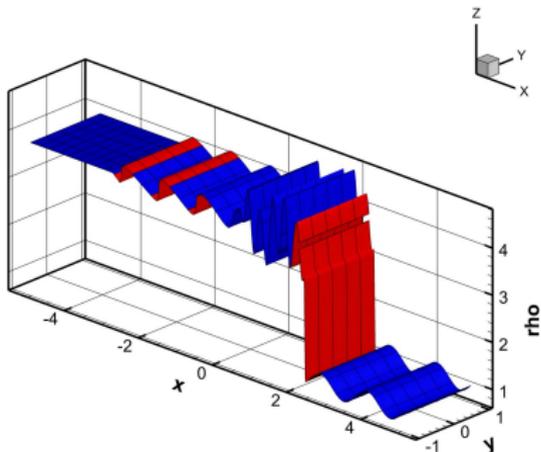
- high-order DG method, high accuracy and compute-bound regimes
- a-posteriori identification of troubled cells
- FV recomputation and DG reconstruction



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DG with FV-based Subcell Limiting:

- high-order DG method, high accuracy and compute-bound regimes
- a-posteriori identification of troubled cells
- FV recomputation and DG reconstruction



ExaHyPE Participants and PIs

University Participants:

- Technische Universität München (coord.): Michael Bader (bader@in.tum.de)
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Industry Participants:

- RSC Group (Russia): Alexander Moskovsky

Project Management and Dissemination:

- BayFOR – Bavarian Research Alliance: Robert Iberl

